

## Newtonian Fluids

A fluid is incompressible Newtonian if:

- 1) Reference mass density uniform:  $\rho_0(x) = \rho_0$
- 2) Fluid is incompressible  $\nabla_x \cdot \underline{v} = 0$

$$\text{Prop 1 + 2} \Rightarrow \rho(x, t) = \rho_0 > 0$$

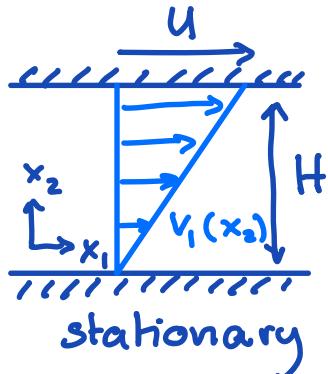
- 3) Cauchy stress field is Newtonian

$$\underline{\underline{\sigma}} = \underline{\underline{\sigma}}^r + \underline{\underline{\sigma}}^a$$

$$\text{Reactive stress: } \underline{\underline{\sigma}}^r = -p \underline{\underline{I}}$$

$p$  is multiplier for  $\nabla_x \cdot \underline{v} = 0$   
same as ideal fluid

Active stress:  $\Rightarrow$  Newton's law of viscosity



Shear force on top plate

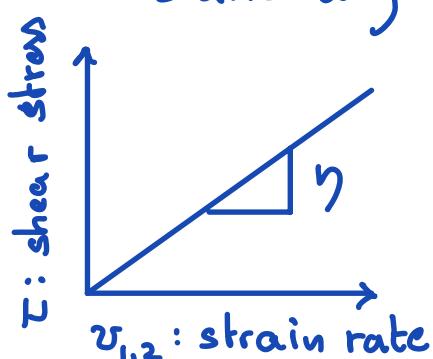
$$F = \eta A \frac{u}{H} \quad A = \text{area of plate}$$

$\eta$  = dynamic/absolute viscosity  
units  $[\frac{N}{LT}]$  e.g. Pa s

$$\text{shear stress: } \tau = \frac{F}{A}$$

$$\boxed{\tau = \eta \frac{\partial v_1}{\partial x_2}} \quad \text{Newton's law}$$

of viscosity



Generalization to 3D

$$\hat{\sigma}_{ij}^a = \mu \frac{\partial \underline{v}_i}{\partial x_j} \Rightarrow \underline{\underline{\sigma}}^a = \mu \underline{\underline{\nabla}} \underline{\underline{\sigma}}$$

but  $\underline{\nabla} \underline{v}$  not objective  $\Rightarrow \underline{\underline{\sigma}}^a = 2\mu \text{sym}(\underline{\nabla} \underline{v})$

$\Rightarrow$  tensor version of classical linear laws

Fourier's law:  $\underline{\underline{q}} = -k \underline{\nabla} T$  (heat conduction)

Fick's law:  $\underline{j} = -D \underline{\nabla} c$  (species diffusion)

Newton's law:  $\underline{\underline{\sigma}} = \gamma \text{sym}(\underline{\nabla} \underline{v})$  (momentum diffusion)

Cauchy stress in Newtonian fluid:

$$\underline{\underline{\sigma}} = -P \underline{\underline{I}} + \gamma (\underline{\nabla} \underline{v} + \underline{\nabla} \underline{v}^\top)$$

In limit  $\gamma \rightarrow 0$  Newtonian fluid reduces to ideal fluid.

Compare to Representation thru with  $A = \underline{\nabla} \underline{v}$ :

$$\underline{\underline{G}}(A) = \lambda \text{tr}(A) \underline{\underline{I}} + 2\mu \text{sym}(A)$$

$$\underline{\underline{G}}(A) = \lambda (\cancel{\nabla \underline{v}}) \underline{\underline{I}} + \mu (\underline{\nabla} \underline{v} + \underline{\nabla} \underline{v}^\top) = \underline{\underline{\sigma}}^a$$

where  $\mu = \gamma$

## Navier - Stokes Equations

Setting  $\rho = \rho_0$  and  $\underline{\underline{\sigma}} = -p \underline{\underline{I}} + \gamma (\nabla \underline{v} + \nabla \underline{v}^T)$   
we obtain lin. mom. balance

$$\rho \dot{\underline{v}} = \nabla \cdot (-p \underline{\underline{I}} + \gamma (\nabla \underline{v} + \nabla \underline{v}^T)) + \rho g$$

assuming  $\gamma = \text{constant}$  we have

$$\nabla \cdot \underline{\underline{\sigma}} = -\nabla p + \gamma \nabla^2 \underline{v} + \gamma \nabla \cdot (\nabla \underline{v})^T$$

Last term

$$\begin{aligned} \nabla \cdot (\nabla \underline{v})^T &= v_{j,i} \epsilon_{ij} = v_{j,j} \epsilon_{ii} = \nabla \cdot (\nabla \cancel{\underline{v}}) \\ \Rightarrow \nabla \cdot \underline{\underline{\sigma}} &= -\nabla p + \gamma \nabla^2 \underline{v} \end{aligned}$$

expanding mat. deriv.:  $\dot{\underline{v}} = \frac{\partial \underline{v}}{\partial t} + (\nabla \underline{v}) \underline{v}$

$$\rho \left[ \frac{\partial \underline{v}}{\partial t} + (\nabla \underline{v}) \underline{v} \right] = \mu \nabla^2 \underline{v} - \nabla p + \rho g$$

$$\nabla \cdot \underline{v} = 0$$

Convective form of Navier-Stokes Equation

## Scaling Navier Stokes Equations

$$\rho \frac{\partial \underline{v}}{\partial t} + (\nabla \underline{v}) \cdot \underline{v} = \eta \nabla^2 \underline{v} - \nabla p + \rho g$$

reduced pressure:  $\pi = p + \rho g z$

$$-\nabla p + \rho g = -\nabla p - \rho g \hat{z} = -\nabla(p + \rho g z) = -\nabla \pi$$

we have

$$\rho \left( \frac{\partial \underline{v}}{\partial t} + (\nabla \underline{v}) \cdot \underline{v} \right) - \eta \nabla^2 \underline{v} = -\nabla \pi$$

Non-dimensionalize with generic quantities  
to define standard dimensionless parameters.

- Dependent variables:  $\underline{v}, \pi$
- Independent variables:  $x, t$
- Parameters:  $\rho \left[ \frac{M}{L^3} \right] \quad \mu \left[ \frac{M}{LT} \right] \rightarrow \nu = \frac{\mu}{\rho} \left[ \frac{L^2}{T} \right]$   
+ Geometry, BC, IC

Use parameters to scale the variables:

$$\underline{v}' = \frac{\underline{v}}{v_c} \quad \pi' = \frac{\pi}{\pi_c} \quad \underline{x}' = \frac{\underline{x}}{x_c} \quad t' = \frac{t}{t_c}$$

Note:  $\underline{v}', \pi', \underline{x}'$  and  $t'$  are dimensionless

substitute into governing equations

$$\rho \frac{v_c}{t_c} \frac{\partial \underline{v}'}{\partial t'} + \rho \frac{v_c^2}{x_c} (\nabla'_x \underline{v}') \underline{v}' - \mu \frac{v_c}{x_c^2} \nabla'^2_x \underline{v}' = - \frac{\pi_c}{x_c} \nabla'_x \pi'$$

Choose to scale to accumulation term

$$\underbrace{\frac{\partial \underline{v}'}{\partial t'}}_{\Pi_1} + \underbrace{\frac{v_c t_c}{x_c} (\nabla'_x \underline{v}') \underline{v}'}_{\Pi_2} - \underbrace{\frac{v t_c}{x_c^2} \nabla'^2_x \underline{v}'}_{\Pi_3} = - \underbrace{\frac{\pi_c t_c}{x_c \rho_0 v_c}}_{\Pi_3} \nabla'_x \pi'$$

where  $\nu = \frac{\gamma}{\rho}$  kinematic viscosity  
 $\nu' \left[ \frac{L^2}{T} \right]$  momentum diffusivity

Three dimensionless groups  $\Rightarrow$  define time scale

$$\Pi_1 = \frac{v_c t_c}{x_c} = 1 \Rightarrow \text{advection scale} \quad t_c = t_A = \frac{x_c}{v_c}$$

$$\Pi_2 = \frac{v t_c}{x_c^2} = 1 \Rightarrow \text{diffusive scale} \quad t_c = t_D = \frac{x_c^2}{\nu}$$

Use  $\Pi_3$  to define pressure scale

$$\Pi_3 = \frac{\pi_c t_c}{x_c \rho_0 v_c} = 1 \Rightarrow \pi_c = \frac{x_c \rho_0 v_c}{t_c}$$

Choose a diffusive time scale  $t_c = \frac{x_c^2}{\nu}$

Dimensionless N-S equation:

$$\frac{\partial \underline{v}}{\partial t} + \frac{v_c x_c}{\nu} (\nabla'_x \underline{v}') \underline{v}' - \nabla'^2_x \underline{v} = - \nabla'_x \pi'$$

$\Rightarrow$  one remaining dim. less group

$$Re = \frac{v_c x_c}{\nu}$$

Reynolds number

ratio of time scales:  $Re = \frac{t_D}{t_A} = \frac{\text{diffusive}}{\text{advective}}$

Hence we have (dropping primes)

$$\frac{\partial \underline{v}}{\partial t} + Re (\nabla \underline{v}) \underline{v} = \nabla^2 \underline{v} - \nabla \pi$$

$\Rightarrow$  only one governing dimensionless parameter: Reynolds number

For viscous flow of glacier:

$$\rho = 10^3 \frac{\text{kg}}{\text{m}^3} \quad v_c = 100 \frac{\text{m}}{\text{yr}} \sim 10^{-6} \frac{\text{m}}{\text{s}}$$

$$\mu = 10^{14} \text{ Pas} \quad x_c = 10^2 \text{ m (thickness)}$$

$$Re = \frac{v_c x_c \rho_0}{\mu c} = \frac{10^{-6+2+3}}{10^{14}} = 10^{-1-14} = 10^{-15} \ll 1$$

$\Rightarrow$  advective momentum transport is negligible

For  $Re=0$  we have

$$\frac{\partial \underline{v}}{\partial t} - \nabla^2 \underline{v} = -\nabla \pi$$

$$\nabla \cdot \underline{v} = 0$$

Equations are linear!

But is it worth resolving diffusive timescale?

$$t_D = \frac{x_c^2 \rho_0}{\mu} = 10^{4+3-14} s = 10^{-7} s$$

This is very short compared to 100 years of glacier response. Not worth resolving transients.

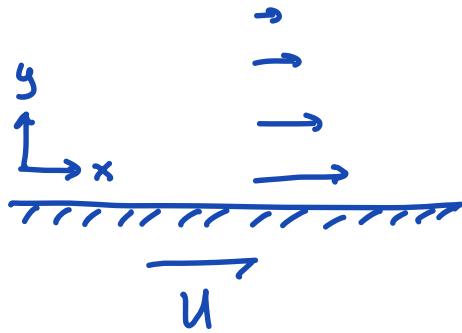
Can't eliminate transient term because we scaled to it  $\Rightarrow$  scale to diffusion term.

## Rayleigh's problem

- Semi-infinite half-space

- Stationary fluid

- Impulsively started plate with velocity  $U$ .



$$v_c = U \rightarrow Re = \frac{U x_c \rho_0}{\mu} \ll 1 \Rightarrow U \ll \frac{\mu}{x_c \rho_0}$$

But what is  $x_c$ ? Not obvious

Re-dimensionalize assuming  $Re \ll 1$

$$\frac{\partial \underline{v}}{\partial t} - \nu \nabla^2 \underline{v} = -\nabla \pi \quad \& \quad \nabla \cdot \underline{v} = 0 \quad \underline{v} = \begin{pmatrix} u \\ w \end{pmatrix}$$

Simplify the equations:

Domain is infinite in  $x$  but  $|\pi| < \infty \Rightarrow \frac{\partial \pi}{\partial x} = 0$

Flow is horizontal:  $\underline{v} = \begin{pmatrix} u \\ 0 \end{pmatrix} \Rightarrow w = 0$

From continuity:  $\frac{\partial u}{\partial x} + \cancel{\frac{\partial w}{\partial y}} = 0 \Rightarrow \frac{\partial u}{\partial x} = 0 \Rightarrow u = u(y)$

$$\nabla^2 \underline{v} = v_{i,j,j} e_i \quad i, j \in \{1, 2\}$$

$$= \begin{pmatrix} v_{1,11} & v_{1,22} \\ v_{2,11} & v_{2,22} \end{pmatrix} = \begin{pmatrix} \cancel{u_{xx}}^e & u_{yy} \\ \cancel{w_{xx}}^e & \cancel{w_{yy}}^e \end{pmatrix} = \begin{pmatrix} u_{yy} \\ 0 \end{pmatrix}$$

Substituting we have

$$x\text{-mom.: } \frac{\partial u}{\partial t} - \nu \frac{\partial^2 u}{\partial x^2} = 0$$

$$y\text{-mom.: } 0 = -\frac{\partial u}{\partial y}$$

$$\Rightarrow \boxed{\frac{\partial u}{\partial t} = \nu \frac{\partial^2 u}{\partial x^2}} \quad \text{with } u(0,y) = 0 \quad u(t,0) = U$$

This is identical to heating a semi-infinite rod from the end.

Problem has self-similar solution in

$$\eta = \frac{y}{\sqrt{4\nu t}} \quad \text{and} \quad u(y,t) = U f(\eta)$$

where  $\sqrt{4\nu t}$  takes role of char. length that depends on  $t$ .

$$\text{derivatives: } \frac{\partial \eta}{\partial t} = -\frac{1}{2} \frac{\eta}{t} \quad \frac{\partial \eta}{\partial y} = \frac{1}{\sqrt{4\nu t}}$$

The derivatives of  $u$  transforms:

$$\frac{\partial u}{\partial t} = U \frac{df}{dy} \frac{\partial \eta}{\partial t} = -\frac{U}{2} \frac{\eta}{t} \quad \text{and} \quad \frac{\partial^2 u}{\partial x^2} = U \frac{d^2 f}{dy^2} \left( \frac{\partial \eta}{\partial x} \right)^2 = \frac{U}{4\nu t} \frac{d^2 f}{dy^2}$$

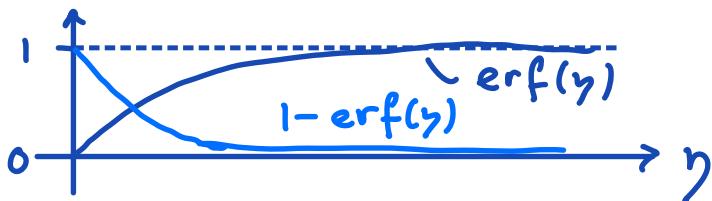
substituting into PDE:

$$\frac{df}{dy^2} + 2y \frac{df}{dy} = 0 \quad \text{with } f(\eta=0) = 1$$

Reduce PDE in  $y$  and  $t$  to ODE in  $\gamma$

Solution :  $f(y) = 1 - \text{erf}(y)$  (Gauss)

where  $\text{erf}(y) = \frac{2}{\sqrt{\pi}} \int_0^y e^{-\xi^2} d\xi$  error function



Resubstituting for  $f = \frac{u}{U}$  and  $\gamma = \frac{y}{\sqrt{4vt}}$

$$u(y, t) = U \left( 1 - \text{erf} \left( \frac{y}{\sqrt{4vt}} \right) \right)$$

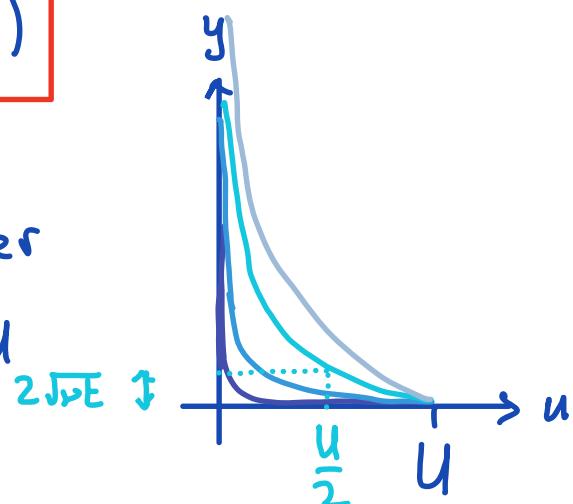
Diffusive boundary layer

where momentum added

by boundary penetrates

into the quiescent fluid.

$\nu = \frac{\mu}{\rho_0}$  is Diffusion coefficient.



## Mechanical energy considerations

Stress power of Newtonian fluid is

$$\underline{\underline{\sigma}} : \underline{\underline{d}} = (-\rho I + 2\mu \underline{\underline{d}}) : \underline{\underline{d}} = -\rho \underbrace{I : \underline{\underline{d}}}_{\nabla_{\underline{x}} \underline{\underline{\sigma}} = 0} + 2\mu \underline{\underline{d}} : \underline{\underline{d}}$$
$$= 2\mu \underline{\underline{d}} : \underline{\underline{d}}$$

From reduced Clausius-Duhem inequality

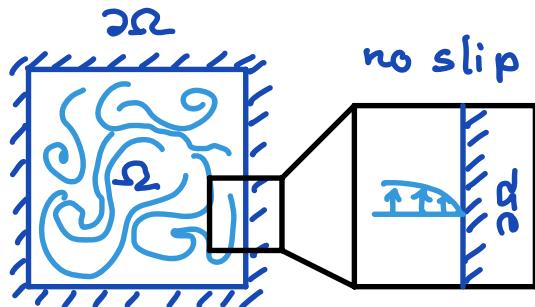
$$\rho \dot{\psi} \leq 2\mu \underbrace{\underline{\underline{d}} : \underline{\underline{d}}}_{> 0}$$

$\Rightarrow$  only if  $\mu > 0$  energy is dissipated during  
flow  $\dot{\psi} < 0$

## Kinetic Energy of Fluid Motion

Dissipation of kinetic energy in a closed domain with no-slip boundaries.

⇒ Energy is lost by boundary



Change in Kinetic energy

$$\frac{d}{dt} K(t) = \int_{\Omega} \frac{1}{2} \rho \frac{d}{dt} |\underline{v}|^2 dV = \int_{\Omega} \rho \dot{\underline{v}} \cdot \underline{v} dV$$

from Navier-Stokes Equa:  $\rho_0 \dot{\underline{v}} = \mu \nabla_x^2 \underline{v} - \nabla \Psi$

$$\frac{d}{dt} K(t) = \int_{\Omega} (\mu \nabla_x^2 \underline{v} - \nabla \Psi) \cdot \underline{v} dV_x$$

1) Integration by parts in fixed domain  $\Omega$   
 with "no slip" boundaries  $\underline{v} = \underline{0}$  on  $\partial\Omega$ .

$$\int_{\Omega} (\nabla_x^2 \underline{v}) \cdot \underline{v} dV_x = - \int_{\Omega} (\nabla_x \underline{v}) : (\nabla_x \underline{v}) dV_x$$

To see this consider  $(v_{ij}, v_i)_{ij} = v_{i,jj} v_i + v_{i,j} v_{i,j}$

$$\begin{aligned} (\nabla_x^2 \underline{v}) \cdot \underline{v} &= v_{i,jj} v_i = (v_{i,j} v_i)_{,j} - v_{i,j} v_{i,j} \\ &= \nabla \cdot ((\nabla_x \underline{v})^T \underline{v}) - (\nabla_x \underline{v}) : (\nabla_x \underline{v}) \end{aligned}$$

substituting into integral and applying div-thm

$$\int_{\Omega} (\nabla_x^2 \underline{v}) \cdot \underline{v} dV_x = \int_{\partial\Omega} (\nabla_x \underline{v})^T \underline{v} \cdot \underline{n} dA_x - \int_{\Omega} (\nabla_x \underline{v}) : (\nabla_x \underline{v}) dV_x$$

2) Poincaré' Inequality

$$\|\underline{u}\|_{\Omega} \leq \lambda \|\nabla \underline{u}\|_{\Omega} \quad \text{for } \underline{u} = 0 \text{ on } \partial\Omega \quad \lambda > 0$$

using standard inner product

$$\int_{\Omega} |\underline{u}|^2 dV_x \leq \lambda \int_{\Omega} \nabla \underline{u} : \nabla \underline{u} dV_x$$

Notice  $\lambda$  has units of  $L^2$  and scales with area  
 of  $\Omega$ .

## Kinetic Energy of Newtonian & Ideal fluids

Consider a fixed domain  $\Omega$  with  $\underline{v} = 0$  on  $\partial\Omega$  and a conservative body force  $\underline{b} = -\nabla_x \underline{\Phi}$ .

The kinetic energy is given by

$$K(t) = \int_{\Omega} \frac{1}{2} \rho_0 |\underline{v}|^2 dV_{\Omega} \quad \text{and} \quad K(0) = K_0$$

### I) Newtonian fluid

$$K(t) \leq e^{-2\mu t / 2\rho_0} K_0$$

The kinetic energy of a Newtonian fluid dissipates to zero exponentially fast.

### II, Ideal fluid

$$K(t) = K_0$$

The kinetic energy of ideal fluid is constant.

show  $\int_{\Omega} \nabla_x \psi \cdot \underline{v} dV_x = 0$

$$\nabla_x \cdot (\psi \underline{v}) = \nabla_x \psi \cdot \underline{v} + (\nabla_x \underline{v}) \cdot \psi = \nabla_x \psi \cdot \underline{v}$$

substitute and use Div-Thm

$$\frac{d}{dt} K(t) = \int_{\Omega} \mu (\nabla_x^2 \underline{v}) \cdot \underline{v} dV_x - \int_{\partial\Omega} \psi \underline{v} \cdot \underline{n} dA_{\partial\Omega}$$

using integration by parts

$$\frac{d}{dt} K(t) = -\mu \int_{\Omega} (\nabla_x \underline{v}) : (\nabla_x \underline{v}) dV_x$$

for ideal fluid  $\mu=0 \Rightarrow K(t) = K_0$

for Newtonian fluid apply Poincaré inequality

$$\frac{d}{dt} K(t) \leq -\frac{\mu}{\lambda} \int_{\Omega} |\underline{v}|^2 dV_x = -\frac{2\mu}{\lambda \rho_0} K(t)$$

so that we have

$$\boxed{\frac{d}{dt} K(t) \leq -\frac{2\mu}{\lambda \rho_0} K(t)}$$

where  $\lambda$  depends on area of the domain.

Solve by separation of parts

$$\frac{dk}{k} \leq -\frac{2H}{\rho_0 \lambda} dt = -\alpha dt$$

$$\ln k \leq -\alpha t + c_0$$

$$k \leq c_1 e^{-\alpha t}$$

Initial condition  $k(0) \leq c_1 = k_0$

$$\Rightarrow k(t) \leq k_0 e^{-\frac{2H}{\lambda \rho_0} t} \quad \checkmark$$

In absence of fluid motion on the boundary  
fluid motion decays exponentially.

The rate of decay depends

$$\nu = \frac{\mu}{\rho_0}$$

kinematic viscosity