

Lecture 5: Boundary conditions

Logistics: - HW1 P1 6/9 P2 5/9

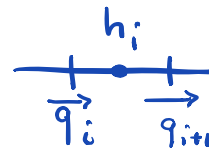
due on Thursday

feel free to work together! Use Piazza!

- HW2 is posted due next Thursday

Last time: - Conservative finite differences

- staggered grid

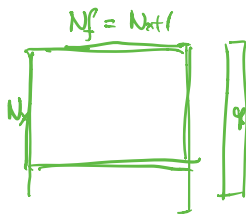


- Discrete operators

$$-\nabla \cdot [K \nabla h] = f_s \quad \text{continuous}$$

$$\nabla \cdot q = f_s$$

$$-\underline{D} * [\underline{K} \underline{G} h] = \underline{f}_s \quad \text{discrete}$$



\underline{D} = discrete divergence matrix $N_{x+1} \cdot N_x$

\underline{G} = discrete gradient matrix $N_x \cdot N_{x+1}$

\Rightarrow sparse diagonals

- adjoint relation: $\underline{G} = -\underline{D}^T$ (in interior)

Today: - Forward testing of operators

- Dirichlet BC \leftrightarrow Constraints

Dirichlet BC's and constraints

→ BC is required for problem to be well posed

$$\underline{L} = -\underline{D} * k * \underline{G}$$

$$\underline{L} \underline{h} = \underline{f}_s$$

$$\underline{h} = \underline{L}^{-1} \underline{f}_s$$

solve lin. sys. with backslash: $\underline{h} = \underline{L} \backslash \underline{f}_s$

not scalable!

~~$$\underline{h} = \text{inv}(\underline{L}) * \underline{f}_s$$~~

is not invertible is singular

⇒ we need BC to make problem well posed.

Example: Highland aquifer

PDE: $-\frac{d}{dx} (bk \frac{dh}{dx}) = f_s$

$x \in [0, L]$

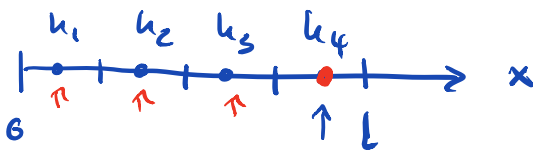
BC:

$h(L) = h_0 = 0$

(homog. Dirichlet BC)

$q(0) = 0 \Rightarrow \frac{dh}{dx}|_0 = 0$

(homog. Neumann BC)
⇒ natural BC



note: Dir. BC is imposed



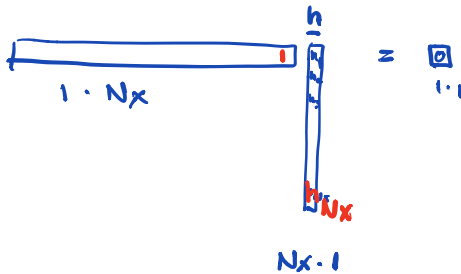
5 km at cell center ⇒ small error

⇒ Dir BC's are constraints

Need to write BC as a lin. system

$$\underline{\underline{B}} \underline{h} = \underline{0}$$

$$h_{Nx} = 0$$



B is a N_c by N_x

matrix, where N_c

is number of constraints
(= cells with Dir. BC)

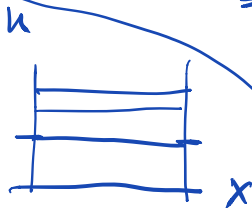
~~$$h_1 - h_2 = 0$$~~

Full statement of discrete problem:

PDE: $\underline{\underline{L}} \underline{h} = \underline{f}_s$ $\underline{\underline{L}} = -\underline{D} \times k \times \underline{G}$ system matrix $N_x \cdot N_x$

BC: $\underline{\underline{B}} \underline{h} = \underline{0}$ $\underline{\underline{B}}$ is constraint matrix $N_c \cdot N_x$

neither $\underline{\underline{L}}$ nor $\underline{\underline{B}}$ are invertible, i.e. unique solutions.



\Rightarrow need to combine $\underline{\underline{L}}$ and $\underline{\underline{B}}$ to

form reduced linear system

$$\underline{\underline{L}}_r \underline{h}_r = \underline{f}_{s,r}$$

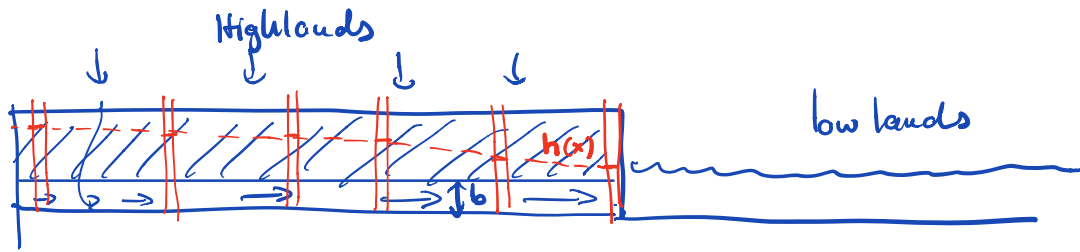
How do we form these

from info above

$\underline{\underline{L}}_r$ is $(N_x - N_c) \cdot (N_x - N_c)$

\underline{h}_r is $(N_x - N_c) \cdot 1$

$\underline{f}_{s,r}$ is $(N_x - N_c) \cdot 1$

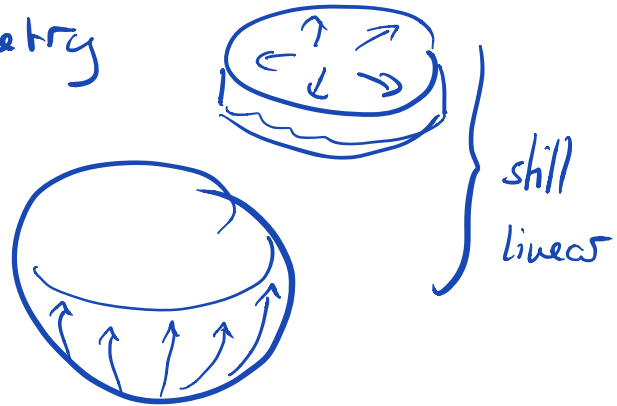


1) starts problem → implement BC

2) → cylindrical symmetry

3) → spherical shell

⇒ update operators



4) unconfined aquifer. → non-linear