

Advection Equation

Porosity evolution equation

$$\frac{\partial \phi_D}{\partial t_D} + \phi_c \nabla_D \cdot [\underline{v}_D \phi_D] = \underbrace{\phi_D^m (h_D - z_D)}_0 + \Delta a \Gamma_D = 0$$

In absence of source terms \rightarrow advection eqn

$$\text{If } p_D = h_D - z_D = 0 \Rightarrow \nabla_D \cdot \underline{v}_D = 0$$

$$\text{Rewrite advective flux: } \nabla_D \cdot [\underline{v}_D \phi_D] = \underline{v}_D \cdot \nabla_D \phi_D + \phi_D \cancel{\nabla_D \cdot \underline{v}_D}$$

Advection eqn in standard form

$$\frac{\partial \phi_D}{\partial t_D} + \phi_c \underline{v}_D \cdot \nabla_D \phi_D = 0$$

In one dimension

$$\frac{\partial \phi_D}{\partial t_D} + \underbrace{\phi_c v_D}_{v = \text{const.}} \frac{\partial \phi_D}{\partial x_D} = 0$$

Drop subscripts : $\boxed{\frac{\partial \phi}{\partial t} + v \frac{\partial \phi}{\partial x} = 0}$

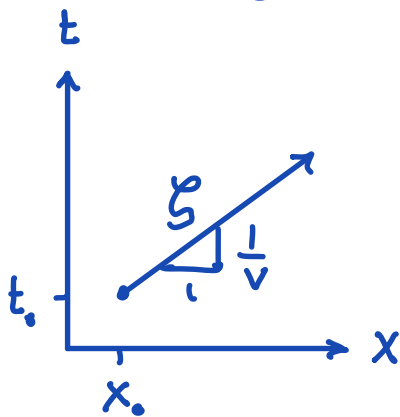
Analytic solution with Method of characteristics

Method of Characteristics

$$\text{PDE: } \frac{\partial \phi}{\partial t} + v \frac{\partial \phi}{\partial x} = 0 \quad x \in \mathbb{R}$$

$$\text{IC: } \phi(x, t=0) = \phi_0(x)$$

Idea: Find a characteristic curve/coordinate, ξ , along which the PDE reduces to an ODE.



$$\phi(x, t) = \phi(x(\xi), t(\xi)) = \Phi(\xi)$$

Total change of Φ along ξ is

$$\frac{d\Phi}{d\xi} = \frac{\partial \phi}{\partial t} \frac{dt}{d\xi} + \frac{\partial \phi}{\partial x} \frac{dx}{d\xi}$$

$$\text{PDE: } \frac{\partial \phi}{\partial t} + v \frac{\partial \phi}{\partial x} = 0$$

By comparison to PDE:

$$\frac{d\Phi}{d\xi} = 0 \Rightarrow \text{solution does not change along}$$

the characteristic curve

$$\frac{dt}{d\xi} = 1, \frac{dx}{d\xi} = v \Rightarrow \frac{dx}{dt} = v \quad \text{"characteristic eqn"}$$

$$\text{solve: } x - x_0 = v(t - t_0)$$

$$\text{from IC: } \phi(x = x_0, t = t_0) = \phi_0(x_0)$$

$$\text{solve char. eqn: } x_0 = x - v(t - t_0)$$

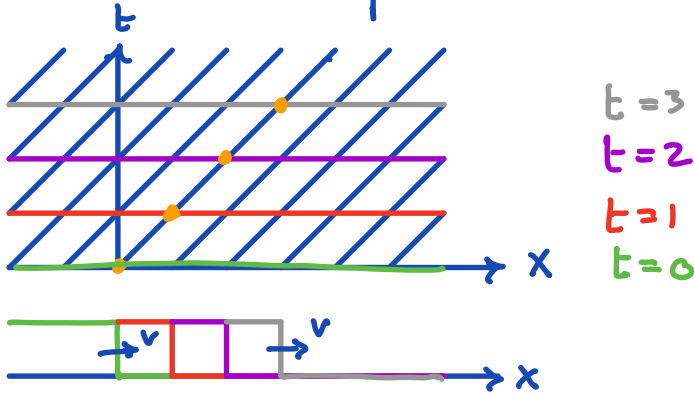
substitute into IC:

$$\phi(x,t) = \phi_0(x - v(t - t_0))$$

gen. solution to adv. eqn.
for any $\phi_0(x)$!

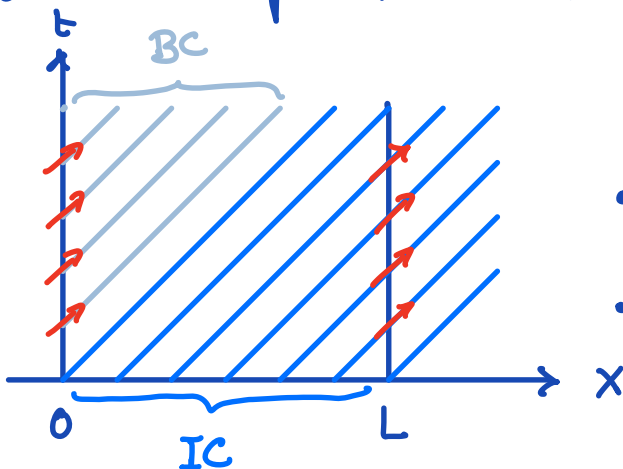
$x - vt =$ travelling wave coordinate ($t_0 = 0$)

The initial profile, ϕ_0 , simply translates with constant shape and velocity to the right ($v > 0$)



Solution is a front moving with const. velocity.

This was on an infinite domain. Now consider a finite domain



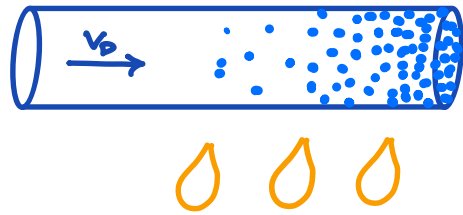
- don't need outflow BC
- need BC on inflow side
- In 2-phase flow the in and out flow bnd depends on phase!

Steady Advection with melting

$$\text{PDE: } \phi_c \nabla \cdot [v_D \phi_D] = \partial_a \Gamma_D \quad x_D \in [0, 1]$$

$$\text{BC: } \phi_D(x_D=0) = 0$$

Pushing a column of ice over a fire and it melts progressively.



Here ϕ_c is not clear because the column is initially not molten.

In 1D $v_D = 1$ and $\Gamma_D = 1$ and we choose $\phi_c = \partial_a$ which corresponds to the final degree of partial melting.

$$\Rightarrow \cancel{\partial_a} \cancel{x_D} \nabla_D \phi_D = \cancel{\partial_a} \cancel{\Gamma_D} \Rightarrow \frac{d\phi_D}{dx_D} = 1$$

integrate $\phi_D - \cancel{\phi_s} = x - \cancel{x_0}$ $\phi_D = x$

Porosity increases linearly in x -dir.

Discretization of Steady Advection

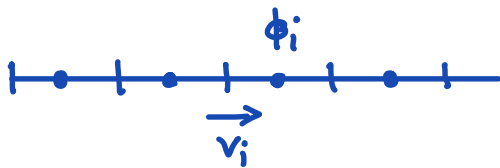
Continuous: $\nabla_D \cdot [\underline{v}_D \phi_D] = 1$

$$\nabla_D \cdot \underline{a}_D = 1 \quad \underline{a}_D = \underline{v}_D \phi_D = \text{adv. flux}$$

Discrete: $\underline{D} \underline{a} = \underline{f}_s$

\underline{a} = discrete advective flux vectors

How to compute \underline{a} from \underline{v} and $\underline{\phi}$?



$\underline{v} = N_f$ by 1 on faces

$\underline{\phi} = N$ by 1 in cells

Advection matrix: $\underline{a} = \underline{A} \underline{\phi}$

$$N_f \cdot 1 \quad N_f \cdot N \quad N \cdot 1$$

\underline{A} is a N_f by N matrix that computes

\underline{a} from $\underline{\phi}$. Shape is same as \underline{G}

$\underline{A} = \underline{A}(\underline{v})$ must be a function of \underline{v} !

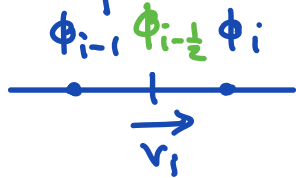
In that case we discretize:

$$\nabla_D \cdot [\underline{v}_D \phi_D] = 1$$

$$\underline{D} \underline{A}(\underline{v}) \underline{\phi} = \underline{f}_s \quad \underline{L} \underline{\phi} = \underline{f}_s \quad \underline{L} = \underline{D} \underline{A}(\underline{v})$$

Construction of \underline{A}

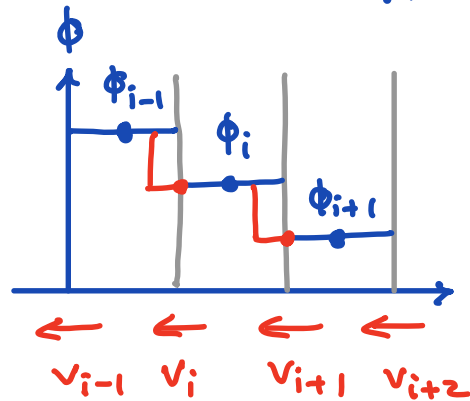
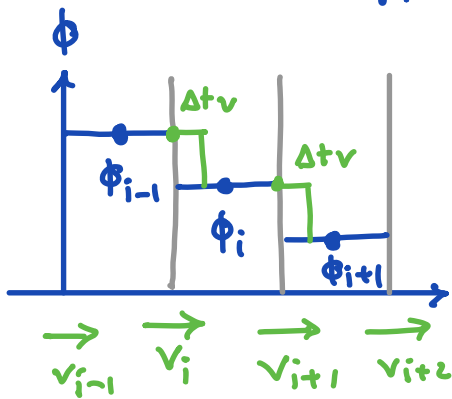
The purpose of \underline{A} is to estimate ϕ on the cell faces and to multiply by v



A horizontal line represents a cell face. Three points are marked on the line: ϕ_{i-1} , $\phi_{i-\frac{1}{2}}$, and ϕ_i . A right-pointing arrow below the line is labeled v_i .

$$a_i = v_i \phi_{i-\frac{1}{2}}$$

How do we approximate $\phi_{i-\frac{1}{2}}$? pp



all $v_i > 0$

$$v_i > 0 : \phi_{i-\frac{1}{2}} = \phi_{i-1}$$

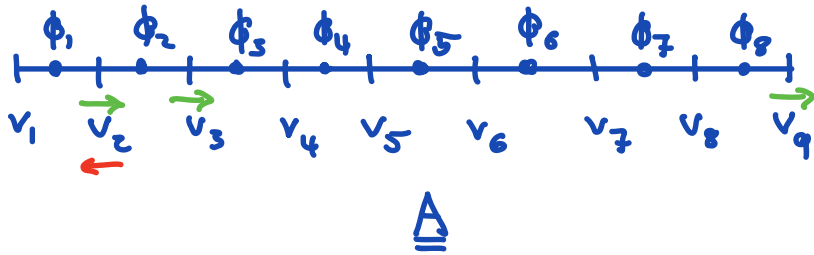
$$v_i < 0 : \phi_{i-\frac{1}{2}} = \phi_i$$

From the analytic solution we know $\phi_{i-\frac{1}{2}}$ depends only on upstream/upwind ϕ values

Natural choice:

$$\phi_{i-\frac{1}{2}} = \begin{cases} \phi_{i-1} & v \geq 0 \\ \phi_i & v < 0 \end{cases}$$

Construction of $\underline{\underline{A}}$



$$\begin{array}{|c|} \hline a_1 \\ \hline a_2 \\ \hline a_3 \\ \hline \end{array} = \begin{array}{|c|} \hline v_1 \\ \hline v_2 \ v_2 \\ \hline v_3 \ v_3 \\ \hline v_4 \ v_4 \\ \hline v_5 \ v_5 \\ \hline v_6 \ v_6 \\ \hline v_7 \ v_7 \\ \hline v_8 \ v_8 \\ \hline v_9 \\ \hline \end{array} \begin{array}{|c|} \hline \phi_1 \\ \hline \phi_2 \\ \hline \phi_3 \\ \hline \phi_8 \\ \hline \end{array}$$

$$a_2 = v_2 \phi_1$$

$$a_3 = v_3 \phi_2$$

$$a_1 = v_1 \phi_1$$

$$\underline{\underline{A}} = \underline{\underline{A}}^+ + \underline{\underline{A}}^-$$

To build $\underline{\underline{A}}$ we need to select appropriate rows of $\underline{\underline{A}}^+$ and $\underline{\underline{A}}^-$ according to sign of the corresponding entry of \underline{v} .

Build pos. and neg. velocity vectors:

$$\underline{v}_n = \min(\underline{v}(1:N_x), 0)$$

$$\underline{v}_p = \max(\underline{v}(2:N_x+1), 0)$$

$$\underline{v} = \begin{bmatrix} 4 \\ -7 \\ 0 \\ -1 \\ -2 \\ 1 \end{bmatrix}$$

$$\underline{v}_n = \begin{bmatrix} 0 \\ -7 \\ 0 \\ -1 \\ -2 \\ 0 \end{bmatrix}$$

$$\underline{v}_p = \begin{bmatrix} 4 \\ 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

given these two vectors we build $\underline{A}(\underline{v})$ as

$$\underline{A} = \begin{bmatrix} 0 & & & & & \\ -1 & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \end{bmatrix}$$

\underline{v}_n
 \underline{v}_p

assemble with spdiags