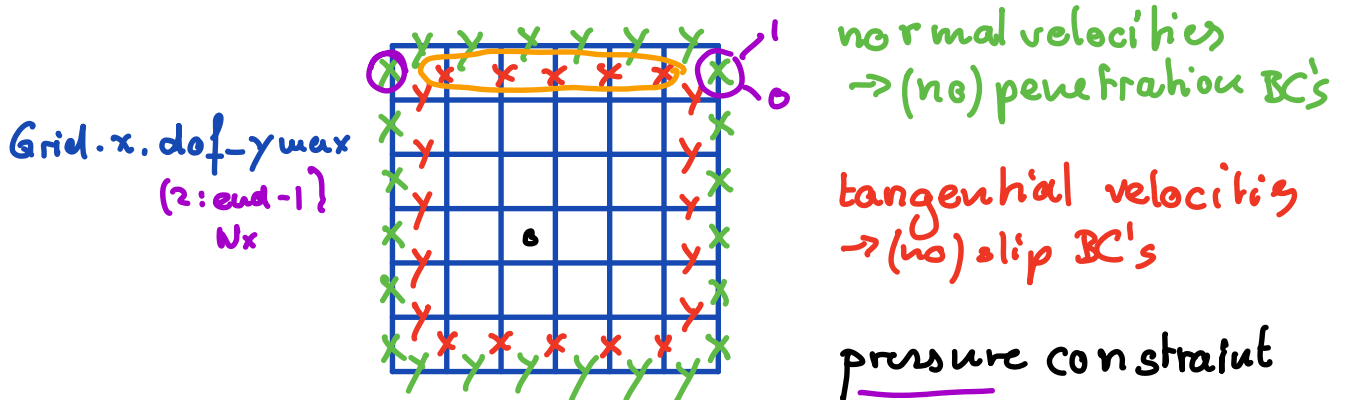


Lecture 23: Streamfunction & Streamlines

Logistics: - HW 8 is due Thursday

Last time: - Implementation of Stokes BC



- need to be careful not to overspecify the BC's → exclude side faces from tangential velocity dof's

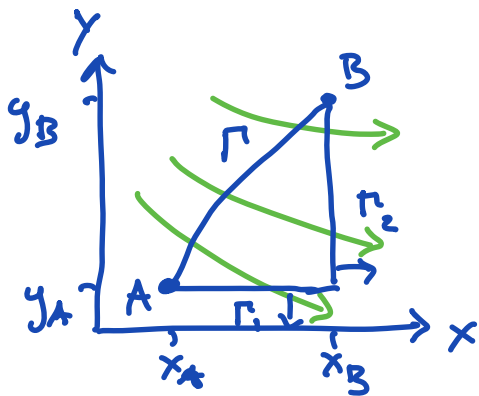
- Streamlines

System ODE's: $\frac{dx}{dt} = \underline{v(x)}$ $\frac{dy}{dx} = \frac{v_y}{v_x}$

Stream function: $\Psi = \int_{\Gamma} \underline{v} \cdot \hat{n} ds$

Today: - Complete discussion of Streamfunction
- Numerical computation of streamfunction

Stream function



$$\psi = \int_{\Gamma} \underline{v} \cdot \hat{n} ds$$

should not depend on path

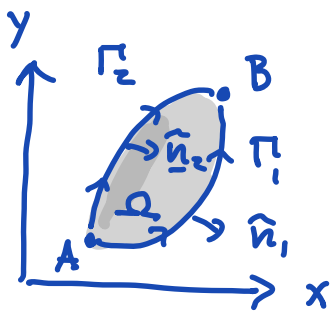
⇒ pick simplest path

$$\psi = \int_{x_A}^{x_B} -v_y(x, y_A) dx + \int_{y_A}^{y_B} v_x(x_B, y) dy$$

From this and FTC we have shown

$$\frac{\partial \psi}{\partial x} = -v_y \quad \frac{\partial \psi}{\partial y} = v_x$$

This conclusion holds if integral is path independent.



If path independent

$$\int_{\Gamma_1} \underline{v} \cdot \hat{n}_1 ds = \int_{\Gamma_2} \underline{v} \cdot \hat{n}_2 ds$$

$$\Rightarrow \int_{\Gamma_1} \underline{v} \cdot \hat{n}_1 ds - \int_{\Gamma_2} \underline{v} \cdot \hat{n}_2 ds = 0$$

Combine the paths $\Gamma = \Gamma_1 + \tilde{\Gamma}_2$ but both Γ_1 & $\tilde{\Gamma}_2$ are from A to B, so flip Γ_2 to go from B to A \Rightarrow changed sign and normal $\hat{n} = \hat{n}_1$ along Γ_1 $\hat{n} = -\hat{n}_2$ along $\tilde{\Gamma}_2$

$$\int_{\Gamma_1} \underline{v} \cdot \hat{n} \, ds + \int_{\tilde{\Gamma}_2} \underline{v} \cdot \hat{n} \, ds = \oint_{\Gamma} \underline{v} \cdot \hat{n} \, ds = 0$$

Integral is path independent if $\oint_{\Gamma} \underline{v} \cdot \hat{n} \, ds = 0$

Using divergence theorem: $\oint_{\Gamma} \underline{v} \cdot \hat{n} \, ds = \int_{\Omega} \nabla \cdot \underline{v} \, dA = 0$

Integral is path independent and streamfunction is well defined if $\nabla \cdot \underline{v} = 0$

- flow is incompressible
- no sources/sinks in Ω

(• discussion has been in 2D)

If first two hold there is a set of two streamfunctions in 3D.

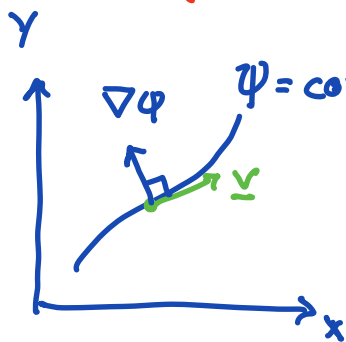
In an incompressible flow without sources/sinks the cumulative flux ψ is a single valued function of \underline{x} and called the streamfunction.

What is the relation between streamfunction and the streamlines?

Relation between ψ and streamlines

1) The level sets/contours of ψ are tangential to the velocity vector everywhere.

\Rightarrow Level sets of ψ are the streamlines



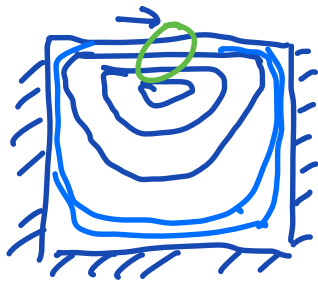
$$\nabla\psi^T \cdot \underline{v} = 0$$

$$\left(\frac{\partial\psi}{\partial x} \quad \frac{\partial\psi}{\partial y} \right) \cdot \begin{pmatrix} v_x \\ v_y \end{pmatrix} = \begin{pmatrix} -v_y & v_x \end{pmatrix} \begin{pmatrix} v_x \\ v_y \end{pmatrix}$$

$$\left. \begin{matrix} \frac{\partial\psi}{\partial x} = -v_y & \frac{\partial\psi}{\partial y} = v_x \end{matrix} \right\} \begin{matrix} \\ \\ \\ \end{matrix} \Rightarrow -v_x v_y + v_x v_y = 0$$

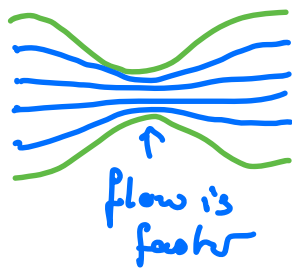
$$\Rightarrow \nabla\psi \perp \underline{v}$$

2) The magnitude of velocity is equal to the magnitude of $\nabla\psi$.



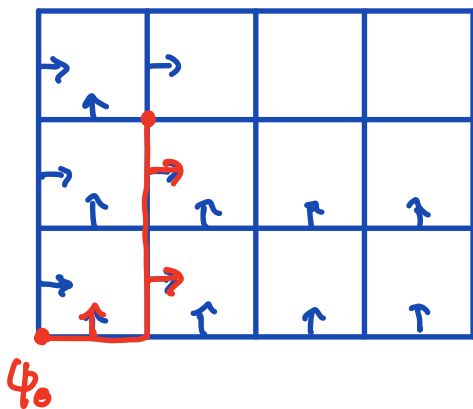
$$|\nabla\psi| = \sqrt{(-v_y)^2 + v_x^2} = \sqrt{v_x^2 + v_y^2} = |\underline{v}|$$

If we plot equally spaced contours of ψ then the spacing between streamlines is inversely proportional to velocity



Computing the Streamfunction

Definition: $\psi(x,y) = \psi_0(x_0, y_0) - \int_{x_0}^x v_y(x', y_0) dx' + \int_{y_0}^y v_x(x, y') dy'$



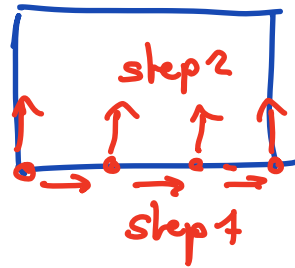
Given the location of the velocities on faces, the natural location to evaluate ψ is in the corners.

Just need to integrate v_x ^{and} v_y along cell boundaries.

Implementation

- Simple Riemann sum is appropriate because \underline{v} is constant along cell face
- Simple implementation with `cumsum.m` which ~~can~~ also works on matrices!

Step 1: Integrate along a bud
with a 1D `cumsum`



Step 2: First reshape the

(x) velocities into appropriate matrix
then you apply a `mat 2D cumsum`
to simultaneously sum integrate all
the columns/rows.

⇒ Stream function as a matrix $(N_y+1) \times (N_x+1)$

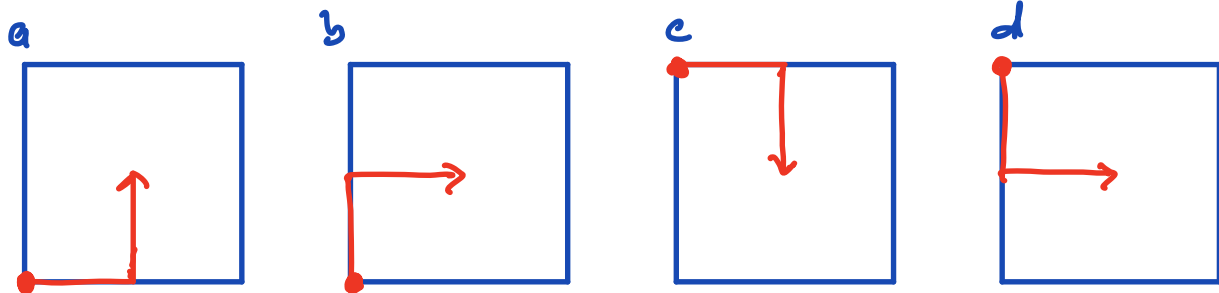
PSI

Note on path independence

ψ is single valued and uniquely defined up to a constant.

In numerical calculation we to choose

- 1) Starting point x_0
- 2) integration path, i.e. x-first or y-first



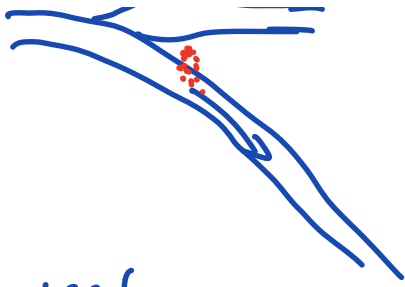
a & b must give same answer by path indep
c & d if starting point is same.

But ψ 's with different starting points
are off set by a constant!

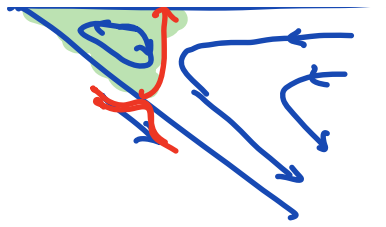
Corner eddies (Keith Moffat)

Subduction zone





real



fluid mechanics

Nice idea thanks fluids guys!

But $\mu = \mu(T)$ the corner of mantle wedge
is very cold \rightarrow viscosity is very high
 \Rightarrow no corner eddy!