

Lecture 29: Last Lecture

Logistics: - that's it

Last time: Darcy-Stokes system

Linear system of 2 equations: (if ϕ is given)

mom.: $\nabla \cdot [\mu_s^* (\nabla \underline{v} + \nabla^T \underline{v})] - \nabla (p_f - \underbrace{S_\phi^* \nabla \cdot \underline{v}_s}) = \bar{\rho} g \hat{z}$

mass: $-\nabla \cdot \left[\frac{k}{\mu} \nabla p_f \right] + \nabla \cdot \underline{v}_s = -\frac{\Delta p}{\rho_f \rho_s} \tau + \nabla \cdot \left(\frac{k}{\mu_f \rho_s} \hat{z} \right)$

Two unknowns: \underline{v}_s p_f

Discretization: $\underline{L} \underline{u} = \underline{f}$

$$\underbrace{\begin{bmatrix} \underline{A} + \underline{G}_p \underline{Z}_d \underline{D}_p & -\underline{G}_p \\ \underline{D}_p & -\underline{D}_p \underline{k}_d \underline{G}_p \end{bmatrix}}_{\underline{L}} \underbrace{\begin{bmatrix} \underline{v}_s \\ p_f \end{bmatrix}}_{\underline{u}} = \underbrace{\begin{bmatrix} \underline{f}_v \\ \underline{f}_p \end{bmatrix}}_{\underline{f}}$$

\underline{Z}_d is N by N diagonal matrix with S_ϕ on the main diagonal.

Today: - Try a head formulation

Try to introduce a potential for Darcy flow because then no flow BC are natural.

Not clear what is the most useful formulation but we'll try to minimize the set up for simplified melt migration equations.

Simplified system:

overpressure: $p = p_f - p_s = p_f - p_L$

$p_L = p_0 + \rho_s g (z_0 - z)$ lithostatic p.

$$\nabla p_L = -\rho_s g \hat{z}$$

$$\begin{aligned} \text{Darcy: } q_r &= -\frac{k}{\mu_f} (\nabla p_f + \rho_f g \hat{z}) \\ &= -\frac{k}{\mu_f} (\nabla p_f - \nabla p_L + \nabla p_L + \rho_f g \hat{z}) \\ &= -\frac{k}{\mu_f} (\nabla (p_f - p_L) - \rho_s g \hat{z} + \rho_f g \hat{z}) \\ &= -\frac{k}{\mu_f} (\nabla p + \Delta \rho g \hat{z}) \quad \Delta \rho = \rho_f - \rho_s > 0 \end{aligned}$$

$$q_r = -\frac{k}{\mu_f} (\nabla p + \Delta \rho g \hat{z})$$

Overpressure head: $h = z + \frac{p}{\Delta \rho g}$

$$p = \Delta \rho g (h - z)$$

$$\nabla p = \Delta \rho g (\nabla h - \hat{z})$$

$$q_r = -\frac{k}{\mu_f} (\Delta \rho g (\nabla h - \hat{z}) + \Delta \rho g \hat{z})$$

$$q_r = -\frac{k \Delta \rho g}{\mu_f} \nabla h = -k \nabla h$$

Substitute into total mass bal:

$$\nabla \cdot [q_r + v_s] = -\frac{\Delta p}{\rho_f \rho_s} \pi$$

$$-\nabla \cdot k \nabla h + \nabla \cdot v_s = -\frac{\Delta p}{\rho_f \rho_s} \pi$$

How does this affect total mass balance?

$$\nabla \cdot [\phi \underline{\underline{\sigma}}_f + (1-\phi) \underline{\underline{\sigma}}_s] = \bar{\rho} g z$$

$$\underline{\underline{\sigma}}_f = -p_f \underline{\underline{I}} \quad \underline{\underline{\sigma}}_s = -p_s \underline{\underline{I}} + \underline{\underline{\tau}}_s$$

$$\underline{\underline{\tau}}_s = \mu (\nabla v_s + \nabla v_s^T - \frac{2}{3} \nabla \cdot v \underline{\underline{I}})$$

$$\nabla \cdot [\phi p_f \underline{\underline{I}} - (1-\phi) p_s \underline{\underline{I}} + (1-\phi) \underline{\underline{\tau}}_s] = \bar{\rho} g z$$

$$p_f - p_L + p_L - p_s = p - \hat{p}_s = \frac{G \mu_s}{\phi^m} \nabla \cdot \underline{v}_s$$

$$\hat{p}_s = p - \frac{G \mu_s}{\phi^m} \nabla \cdot \underline{v}_s$$

substitute

$$\bar{p} = \phi p + (1 - \phi) \left(p - \frac{G \mu_s}{\phi^m} \nabla \cdot \underline{v}_s \right) + p_L$$

$$= \phi p + (1 - \phi) p - \underbrace{\frac{1 - \phi}{\phi^m} G \mu_s}_{S_\phi} \nabla \cdot \underline{v}_s + p_s$$

$$\bar{p} = p - S_\phi \nabla \cdot \underline{v}_s + p_L$$

$$h = z + \frac{p}{\Delta \rho g}$$

$$p_L = p_0 + \rho_s g (z_0 - z)$$

$$p_L = -\rho_s g z$$

$$p = \Delta \rho g (h - z)$$

substitute

$$\bar{p} = \Delta \rho g (h - z) - S_\phi \nabla \cdot \underline{v}_s - \rho_s g z$$

$$= \Delta \rho g h - S_\phi \nabla \cdot \underline{v}_s - (\rho_f - \rho_s) g z - \rho_s g z$$

$$= \Delta \rho g h - S_\phi \nabla \cdot \underline{v}_s + (-\rho_f + \cancel{\rho_s} - \cancel{\rho_s}) g z$$

$$\bar{p} = \Delta p g h - \Sigma_{\phi} \nabla \cdot \underline{v}_s \quad \text{(- } \rho_f g z \text{)}$$

substitute into total momentum:

$$\nabla \cdot [-\bar{p} \underline{I} + (1-\phi) \underline{\tau}_s] = \bar{p} g \hat{z} = (\phi \rho_f + (1-\phi) \rho_s) g \hat{z}$$

$$\nabla \cdot [\Delta p g h + \Sigma_{\phi} \nabla \cdot \underline{v}_s + (1-\phi) \underline{\tau}_s] = \phi \rho_f g \hat{z} + (1-\phi) \rho_s g \hat{z}$$

$$\nabla \cdot [(-\Delta p g h + \Sigma_{\phi} \nabla \cdot \underline{v}_s) \underline{I} + (1-\phi) \underline{\tau}_s] = -\rho_f g \hat{z} + \phi \rho_f g \hat{z} + (1-\phi) \rho_s g \hat{z}$$

$$= -(1-\phi) \rho_f g \hat{z} + (1-\phi) \rho_s g \hat{z}$$

$$= -(1-\phi) \Delta p g \hat{z}$$

$$\nabla \cdot [(-\Delta p g h + \Sigma_{\phi} \nabla \cdot \underline{v}_s) \underline{I} + (1-\phi) \underline{\tau}_s] = -(1-\phi) \Delta p g \hat{z}$$

$$\nabla \cdot [\mu_s^* (\nabla \underline{v}_s + \nabla^T \underline{v}_s)] + \Delta p g \nabla (h - \frac{\Sigma_{\phi}^*}{\Delta p g} \nabla \cdot \underline{v}_s) = -(1-\phi) \Delta p g \hat{z}$$

$$\Sigma_{\phi}^* = \frac{1-\phi}{\phi \mu} G \mu_s - \frac{2}{3} \mu_s (1-\phi)$$

$$= \left(\frac{G}{\phi \mu} - \frac{2}{3} \right) \mu_s (1-\phi)$$

$$\underline{\underline{\tau}} = \underline{\underline{\tau}} \cdot \underline{\underline{v}}$$

$$= \mu \underline{\underline{E}} \dot{\underline{\underline{\sigma}}} +$$

$$\underline{\underline{E}} \dot{\underline{\underline{\sigma}}} = \begin{bmatrix} G_{xx} & \frac{2}{3} D_p \\ \frac{2}{3} D_p & G_{yy} \\ \frac{1}{2} G_{xy} & \frac{1}{2} G_{yx} \end{bmatrix} \begin{bmatrix} v_x \\ v_y \\ p \end{bmatrix}$$

$$\underline{\underline{E}} \dot{\underline{\underline{\sigma}}} v_x = \underline{\underline{\epsilon}} \dot{\underline{\underline{\sigma}}} = \begin{bmatrix} \epsilon \dot{\underline{\underline{\sigma}}}_{xx} \\ \epsilon \dot{\underline{\underline{\sigma}}}_{yy} \\ \epsilon \dot{\underline{\underline{\sigma}}}_{xy} \end{bmatrix}$$

$$\underline{\underline{\tau}} = \mu \begin{bmatrix} G_{xx} - \frac{2}{3} D_p & -\frac{2}{3} D_p \\ -\frac{2}{3} D_p & G_{yy} - \frac{2}{3} D_p \\ \frac{1}{2} G_{xy} & \frac{1}{2} G_{yx} \end{bmatrix} \begin{bmatrix} v_x \\ v_y \end{bmatrix}$$

- $\underline{\underline{D}} * \underline{\underline{q}} = \underline{\underline{f}}$
 $\underline{\underline{q}} = -\kappa \underline{\underline{G}} \underline{\underline{h}}$