

# Lecture 5: Shallow Aquifer Models & Boundary Conditions

Logistics: - Today outline (Marc is sick)

- Thursday will be freezing

→ likely UT will open late

→ stay online for now

- HW 1 is due Th 9:30 am

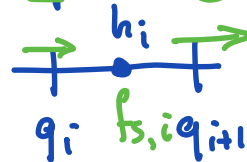
- Office hours 4-5 pm Wed.

Last time: - Discrete operators

$$1) \nabla \cdot \underline{q} = \underline{f_s} \rightarrow \underline{D} \underline{q} = \underline{f_s}$$

$$2) \underline{q} = -K \nabla h \rightarrow \underline{q} = -K \underline{G} \underline{h}$$

Staggered grid



$$\underline{G} = \frac{1}{\Delta x} \begin{bmatrix} 0 & & & & \\ -1 & & & & \\ & 1 & & & \\ & & -1 & & \\ & & & 1 & \\ & & & & -1 & \\ & & & & & 1 & \\ & & & & & & -1 & \\ & & & & & & & 1 & \\ & & & & & & & & -1 & \\ & & & & & & & & & 1 & \\ & & & & & & & & & & -1 & \\ & & & & & & & & & & & 1 & \\ & & & & & & & & & & & & -1 & \\ & & & & & & & & & & & & & 1 & \\ & & & & & & & & & & & & & & -1 & \\ & & & & & & & & & & & & & & & 1 \end{bmatrix}$$

$N_x + 1$  by  $N_x$

cell centers → cell faces

$$\underline{D} = \frac{1}{\Delta x} \begin{bmatrix} 0 & & & & \\ & -1 & & & \\ & & 1 & & \\ & & & -1 & \\ & & & & 1 & \\ & & & & & -1 & \\ & & & & & & 1 & \\ & & & & & & & -1 & \\ & & & & & & & & 1 & \\ & & & & & & & & & -1 & \\ & & & & & & & & & & 1 & \\ & & & & & & & & & & & -1 & \\ & & & & & & & & & & & & 1 & \\ & & & & & & & & & & & & & -1 & \\ & & & & & & & & & & & & & & 1 & \\ & & & & & & & & & & & & & & & -1 & \\ & & & & & & & & & & & & & & & & 1 \end{bmatrix}$$

$N_x$  by  $N_x + 1$   
faces → centers

Today: • Introduce shallow aquifer model

→ 1D model problem

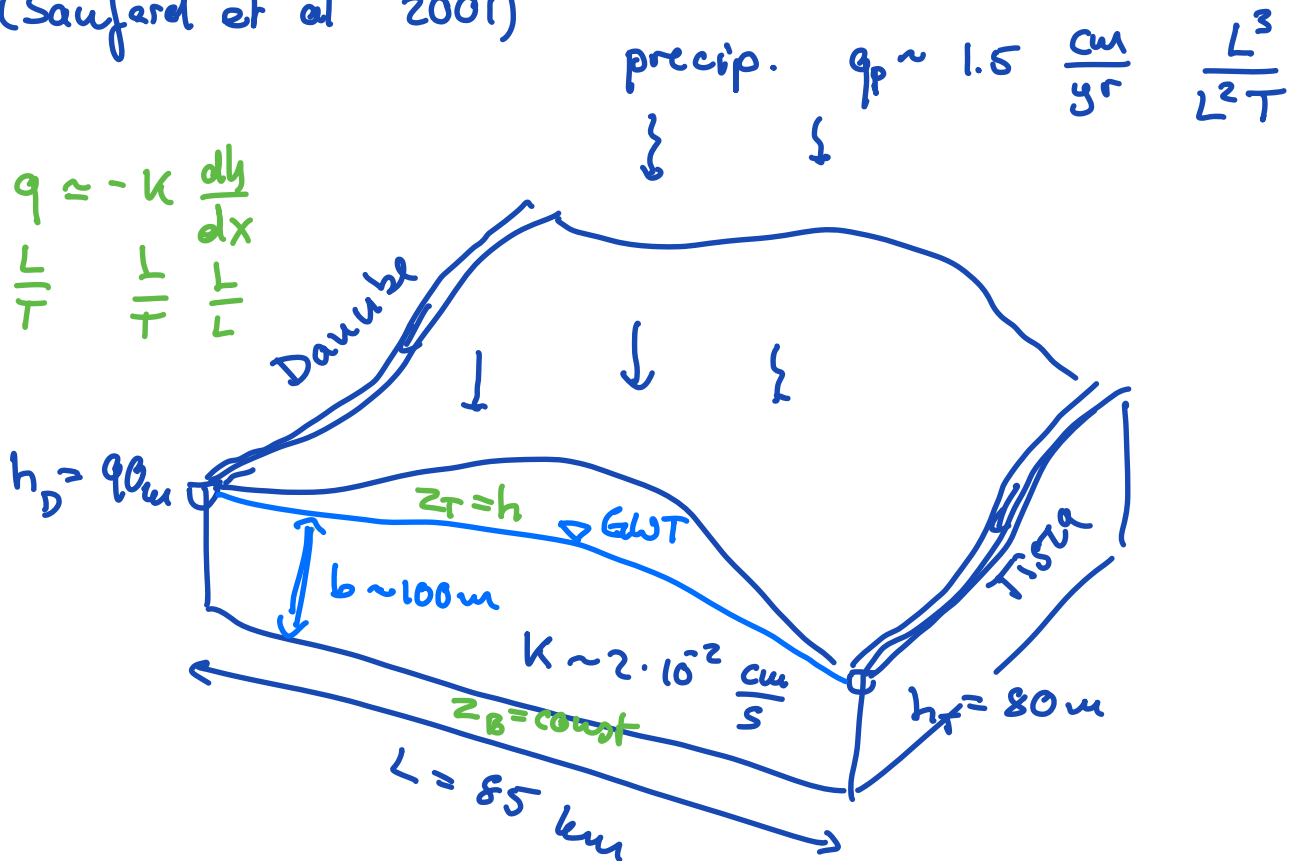
→ motivate BC's

• Dirichlet BC's

→ using constraints

Ground water recharge between two rivers

(Sauter et al 2001)



Aquifer aspect ratio:  $b/L = \frac{100\text{m}}{85000\text{m}} \approx 1$

85 000 m 1000  
 $\Rightarrow$  flow is practically 1D in horizontal direction

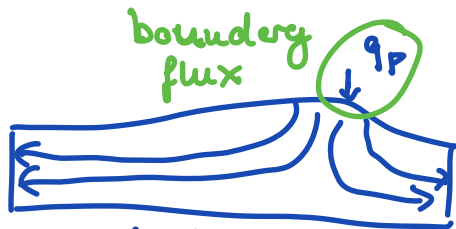
This can be seen from scaling analysis of the continuity equ.:

$$x_D = \frac{x}{L} \quad z_D = \frac{z}{b}$$

$$q_{x,D} = \frac{q_x}{q_{x,c}}$$

$$q_{z,D} = \frac{q_z}{q_{z,c}}$$

$$q_{z,c} = q_p$$



$$q_x = \underbrace{q_{x,c}}_{\text{const}} \underbrace{q_{x,D}}_{\text{varies}}$$

substitute into continuity equ.:

$$\nabla \cdot q = \frac{\partial q_x}{\partial x} + \frac{\partial q_z}{\partial z} = \frac{q_{x,c}}{L} \frac{\partial q_{x,D}}{\partial x_D} + \frac{q_{z,c}}{b} \frac{\partial q_{z,D}}{\partial z_D} = 0$$

collect terms

$$\frac{\partial q_{x,D}}{\partial x_D} + \underbrace{\frac{q_{z,c} L}{q_{x,c} b}}_{\Pi} \frac{\partial q_{z,D}}{\partial z_D} = 0$$

$\Pi = 1$  suggest the relation between scales

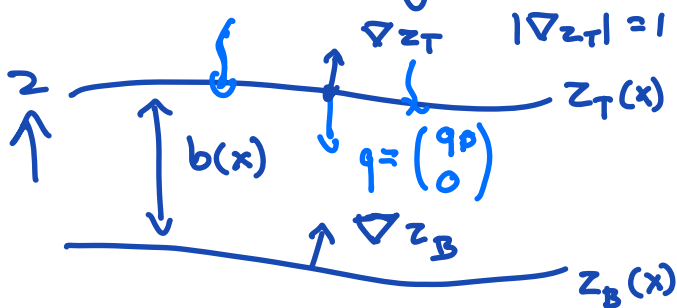
$$\frac{q_{z,c}}{q_{x,c}} \frac{L}{b} = 1 \quad \Rightarrow \quad q_{z,c} = \frac{b}{L} q_{x,c} \sim 10^{-3} q_{x,c}$$

the vertical fluxes are approx. 1000 times smaller than horizontal flux!

Assume  $q_z = 0 \Rightarrow \frac{\partial h}{\partial z} = 0 \Rightarrow h = h(x)$   
 implies that pressure is hydrostatic in  
 vertical.

Darcy:  $q_x = -k \frac{\partial h}{\partial x}$

### Vertical integration



$$b(x) = z_T(x) - z_B(x)$$

$$\nabla \cdot \mathbf{q} = 0$$

$$\int_{z_B}^{z_T} \nabla \cdot \mathbf{q} \, dz \stackrel{?}{=} \nabla \cdot \int_{z_B}^{z_T} \mathbf{q} \, dz$$

Leibnitz integral rule:

$$\int_{z_B}^{z_T} \nabla \cdot \mathbf{q} \, dz = \nabla \cdot \int_{z_B}^{z_T} \mathbf{q} \, dz + \left( \mathbf{q} \cdot \nabla z_B \Big|_{z_B} - \mathbf{q} \cdot \nabla z_T \Big|_{z_T} \right)$$

Assumptions:

$$1) \quad \mathbf{q} = \begin{pmatrix} q_x(x) \\ 0 \end{pmatrix} \Rightarrow \mathbf{q} \neq \mathbf{q}(z)$$

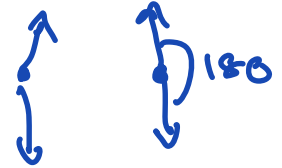
$$\int_{z_B}^{z_T} q \, dz = q (z_T - z_B) = b(x) q(x)$$

2) bottom of aquifer is impermeable

$$q \cdot \nabla z_B |_{z_B} = q \cdot \hat{n}_B |_{z_B} = 0$$

3) slope of top of aquifer is negligible

$$q \cdot \nabla z_T |_{z_T} = q \cdot \hat{n}_T |_{z_T} = -q_p$$



Substitute into vertically integrated eqn.

$$\int_{z_B}^{z_T} \nabla \cdot q \, dz = 0 \Rightarrow -\tilde{\nabla} \cdot [b k \tilde{\nabla} h] = q_p$$

$\tilde{\nabla}$  horizontal components of operator

full eqn:  
3D & 2D

$$-\nabla \cdot [k \nabla h] = 0$$

$$q \cdot \hat{n}_T |_{z_T} = q_p$$

$$q \cdot \hat{n}_B |_{z_B} = 0$$

shallow approx:  $-\tilde{\nabla} \cdot [b k \tilde{\nabla} h] = q_p$

In 1D

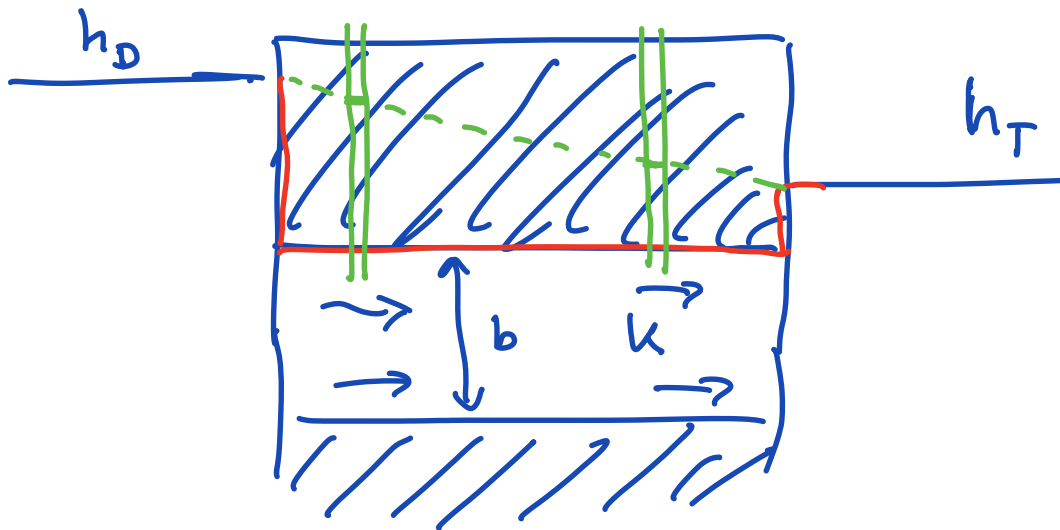
$$-\frac{d}{dx} [b k \frac{dh}{dx}] = q_p$$

Note:

In an unconfined aquifer  $z_T = h$  free surface

$$-\tilde{\nabla} \cdot [K h \tilde{\nabla} h] = q_p \quad \text{non-linear}$$

Here we assume  $b = \text{const} \Rightarrow$  confined aquifer



linear problem  $\rightarrow$  start.

Simplified example problem:

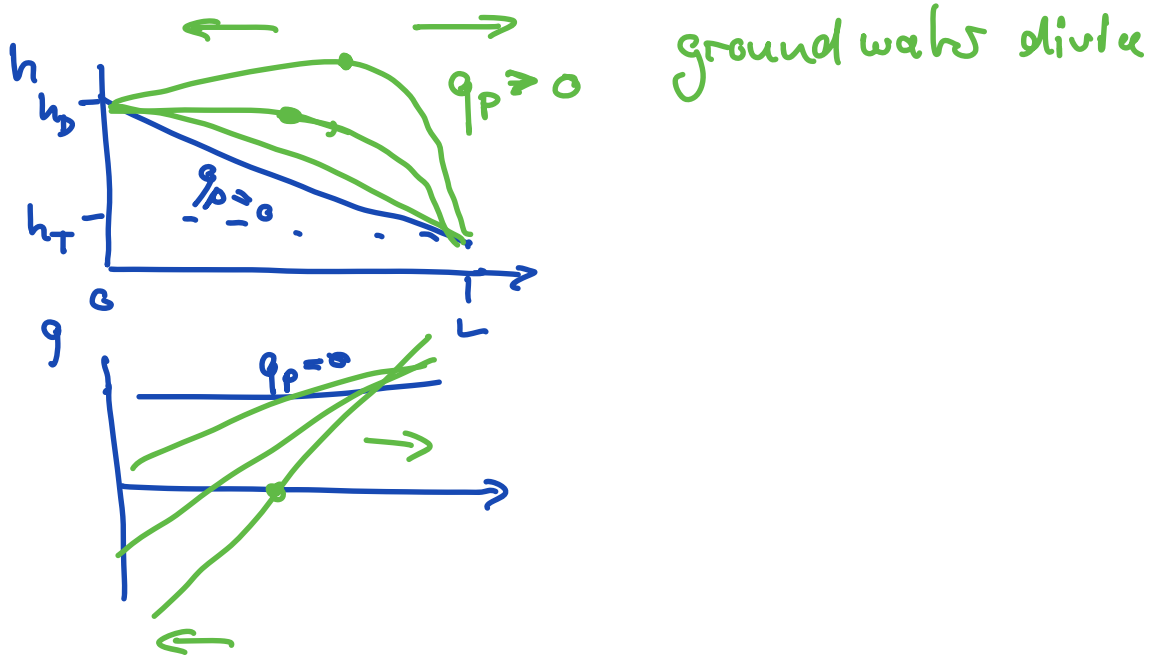
$$\text{PDE: } -\frac{d}{dx} [b K \frac{dh}{dx}] = q_p \quad x \in [0, L]$$

$$\text{BC: } h(0) = h_D \quad h(L) = h_T$$

integrate twice to obtain analytic solution

$$h = h_D + \left( \frac{h_T - h_D}{L} + \frac{q_p L}{2bk} \right) x - \frac{q_p}{2bk} x^2$$

$$q = \frac{q_p}{b} \left( x - \frac{L}{2} \right) - \frac{k}{L} (h_T - h_D)$$



## Dirichlet boundary conditions

BC's are necessary for the problem to be well posed, i.e., unique solution. Dirichlet BC's prescribe the unknown on bound. This provides constraints on solution unknowns that reduce the number of unknowns we need to solve for.

⇒ need to understand how to eliminate constraints from our system.

Example 1: Homogeneous BC's

$$\text{PDE: } -\frac{d}{dx} \left[ b_k \frac{dh}{dx} \right] = q_r \quad x \in [0, L]$$

$$\text{BC: } h(0) = h(L) = 0$$

We can use discrete operators to write

PDE as system of linear equations

$$\underline{\underline{L}} \underline{h} = \underline{f}_s \quad \underline{\underline{L}} = -\underline{\underline{D}} * \underline{\underline{G}} \quad \underline{f}_s = \frac{q_r}{b_k} \underline{1}$$

$\underline{\underline{L}}$  is not invertible!

⇒ need to eliminate constraints from BC

to make invertible matrix

Write ~~the~~ BC's as a linear system.

$$h(0) = 0 \quad h(L) = 0$$

$$h_1 = 0 \quad h_{N_x} = 0$$

Note: Imposing Dir. BC's at cell center.



$$\underline{\underline{B}} \underline{h} = \underline{0}$$

$\underline{\underline{B}}$  is a  $N_c$  by  $N_x$  constraint matrix  
 $\uparrow$   
 # of constraints

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots \\ c & e & c & r \end{bmatrix} \underline{h} = \underline{0}$$

$h_1 = 0$   
 $0 = 0$

Full discrete problem statement

PDE :  $\underline{\underline{L}} \underline{h} = \underline{f}_s$        $\underline{\underline{L}}$  is  $N_x$  by  $N_x$  system matrix

BC :  $\underline{\underline{B}} \underline{h} = \underline{0}$        $\underline{\underline{B}}$  is  $N_c$  by  $N_x$  constraint mat.

Neither system is solvable individually

$\Rightarrow$  need to combine them by eliminating the

constraints  $\underline{\underline{B}}$  from  $\underline{\underline{L}}$  to produce a

"reduced" system  $\underline{\underline{L}}_r$  ( $N_x - N_c$ ) by ( $N_x - N_c$ )