

## Lecture 6: Shallow aquifer model

Logistics: - HW1 due next Thursday

Last time: - Discrete operators

-  $\underline{\underline{G}}$  discrete gradient  $N_x$  by  $N_x$

$h$  in cell center  $\rightarrow$   $dh$  ( $q$ ) on cell faces

-  $\underline{\underline{D}}$  discrete divergence  $N_x$  by  $N_x$

$q$  on cell faces  $\rightarrow$   $dq$  in cell center

$$\underline{\underline{G}} = -D^T$$

-  $\underline{\underline{M}}$  mean operator  $N_x$  by  $N_x$

$h$  in cells  $\rightarrow$   $mh$  on faces

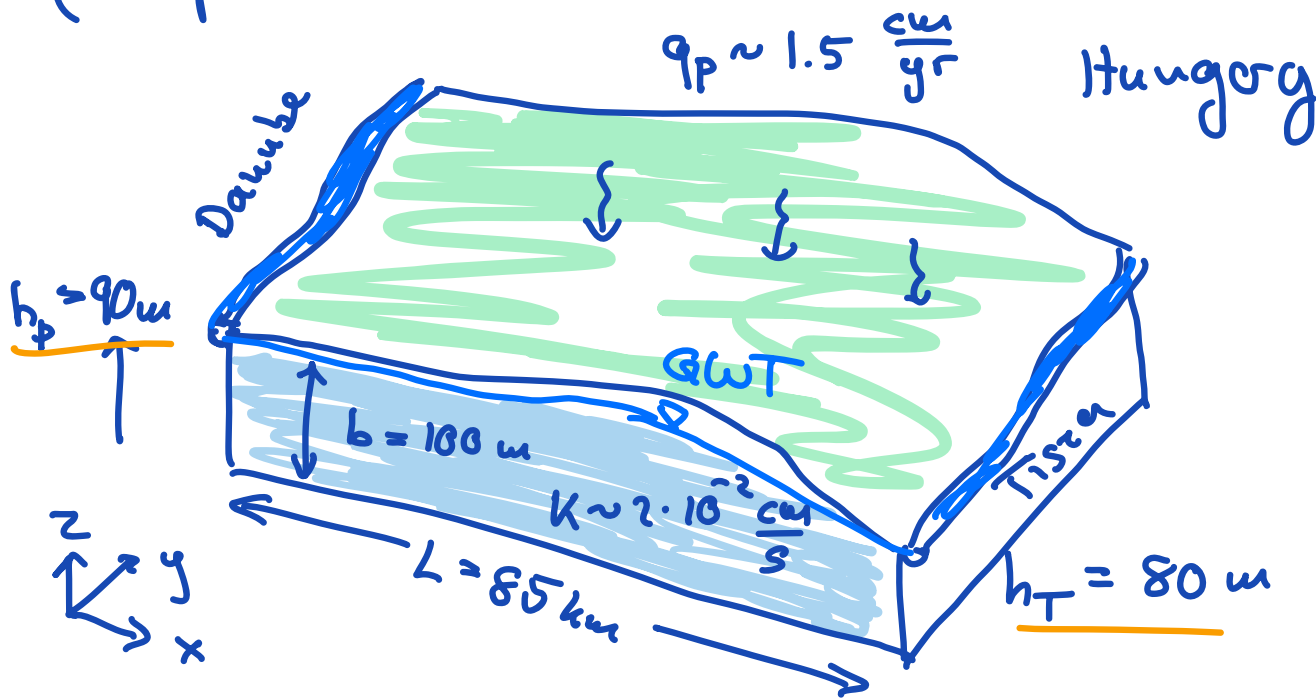
-  $\underline{\underline{L}} = \underline{\underline{D}} \underline{\underline{G}}$  Laplacian  $N_x$  by  $N_x$

Today: - Shallow aquifer model

- Dirichlet boundary conditions

# Groundwater recharge between two rivers

(Saufsdal et al. 2001)



Aspect ratio of aquifer:  $b/L = \frac{100}{85000} = \frac{1}{850} \sim 0.001$   
 $\Rightarrow$  flow is practically horizontal  $\sim 1D$

You can show this by scaling analysis  
of continuity equation  $\nabla \cdot \mathbf{q} = f_s \rightarrow 0$

Introduce characteristic scales:

$$x_D = \frac{x}{L} \quad z_D = \frac{z}{b} \quad q_{x,D} = \frac{q_x}{q_{x,c}} \quad q_{z,D} = \frac{q_z}{q_{z,c}}$$

of few some scales are not clear

substitute:

$$\nabla \cdot q = \frac{\partial q_x}{\partial x} + \frac{\partial q_z}{\partial z} = \frac{q_{x,c}}{L} \frac{\partial q_{x,D}}{\partial x_D} + \frac{q_{z,c}}{b} \frac{\partial q_{z,D}}{\partial z_D} = 0$$

$$\frac{\partial q_{x,D}}{\partial x_D} + \underbrace{\frac{q_{z,c} L}{q_{x,c} b}}_{\Pi} \frac{\partial q_{z,D}}{\partial z_D} = 0$$

$\Pi$  dimensionless parameter

Set  $\Pi = 1$  get relation between fluxes

$$\boxed{q_{z,c} = \frac{b}{L} q_{x,c}} \Rightarrow \text{vertical flux is negligible}$$

$\uparrow$   
0.001

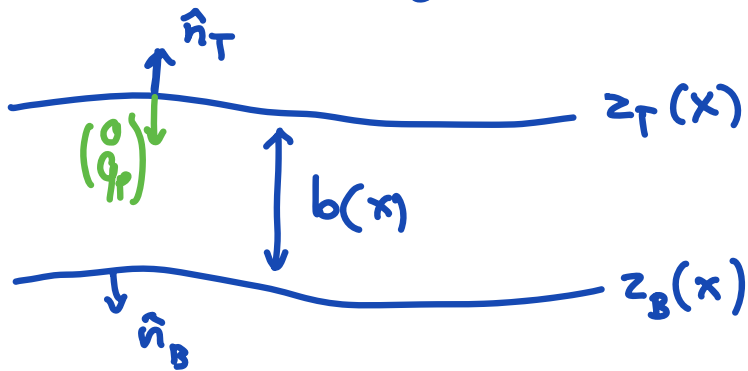
Assume  $q_z = 0 \Rightarrow \frac{\partial h}{\partial z} = 0 \Rightarrow h = h(x, y)$

$$q_z = -k \frac{\partial h}{\partial z}$$

Darcy:  $q_h = \begin{pmatrix} q_x \\ q_y \end{pmatrix} = -k \nabla_h h$   $\nabla_h h = \begin{pmatrix} \frac{\partial h}{\partial x} \\ \frac{\partial h}{\partial y} \end{pmatrix}$

$\uparrow$   
horizontal gradient

# Vertical integration



$$b(x) = z_T(x) - z_B(x)$$

$$\int_{z_B(x)}^{z_T(x)} \nabla \cdot \mathbf{q} \cdot dz = ?$$

Need to exchange integral and derivative  
but  $z_T$  &  $z_B$  depend on  $x$ !

Standard Leibnitz integral rule:

$$\frac{d}{dx} \int_{a(x)}^{b(x)} f(x, z) dz = \int_{a(x)}^{b(x)} \frac{df}{dx} dz + \underbrace{f(x, b(x)) \frac{db}{dx}} - f(x, a(x)) \frac{da}{dx}$$

Here we need slightly different version (Pinder & Gray)

$$\int_{z_B}^{z_T} \nabla \cdot \mathbf{q} dz = \nabla_n \cdot \int_{z_B}^{z_T} \underline{q_n} dz + (\hat{n} \cdot \mathbf{q})|_{z_T} - (\hat{n} \cdot \mathbf{q})|_{z_B}$$

since  $q_n \neq q_n(z)$

$$\Rightarrow \nabla_n \cdot \int_{z_B}^{z_T} q_n dz = \nabla_n \cdot \left( q_n \Big|_{z_B}^{z_T} dz \right) = \nabla_n \cdot (b q_n)$$

Boundary terms:

Bottom is impermeable:  $(\hat{n} \cdot \mathbf{q})|_B = 0$

Top:  $(\hat{n} \cdot \mathbf{q})|_{z_T} = -q_p$

Substitute:  $\nabla_n \cdot (b q_n) = q_p = 0$

Darcy:  $q_n = -k \nabla_n h$

$\Rightarrow$   $-\nabla_n \cdot (bK \nabla_n h) = q_p$  2D shallow aquifer model (saturated) confined

Note:  $z_T$  is water table?

$$z_T = h$$

$$z_B = 0$$

$$\Rightarrow b = h$$

In 1D we have:  $-\frac{d}{dx} [bk \frac{dh}{dx}] = q_p$

Simplified example problem:

$$\text{PDE: } -\frac{d}{dx} [bk \frac{dh}{dx}] = q_p \quad x \in [0, L]$$

$$\text{BC: } h(0) = h_D \quad h(L) = h_T$$

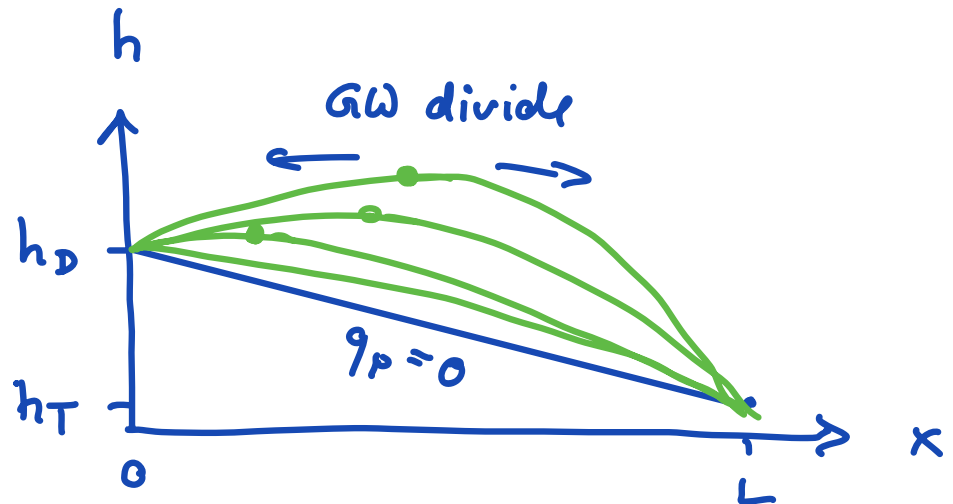
$b, k, q_p = \text{const.}$

Integrate twice to obtain analytic solution:

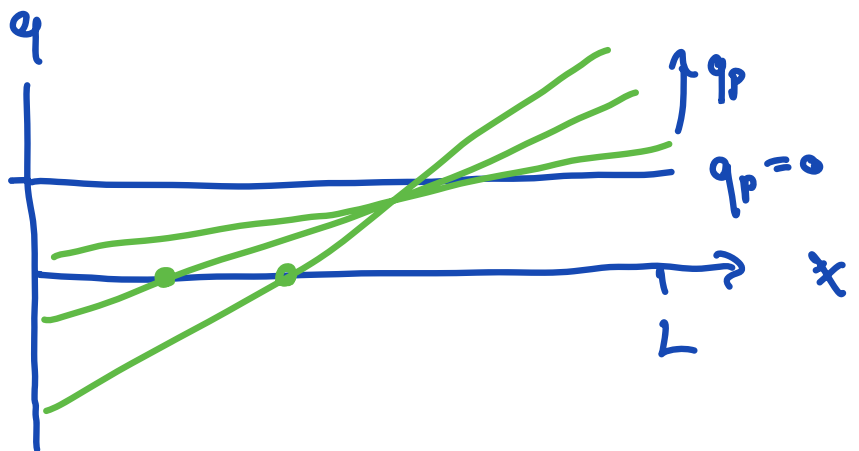
$$h = h_D + \left( \frac{h_T - h_D}{L} + \frac{q_p L}{2bk} \right) x - \frac{q_p}{2bk} x^2$$

$$q = \frac{q_p}{b} \left( x - \frac{L}{2} \right) - \frac{k}{L} (h_T - h_D)$$

Sketch solution



As recharge/precipitation increases a "ground water divide" forms that separates water flowing into Danube from water flowing into Tisza river.



⇒ solve numerically

# Dirichlet BC and Constraints

BC are required for problem to be well posed!

Dir BC specify  $h$  on bnd.

⇒ constraints on solution

⇒ reduces the number of unknowns

Need to learn how to eliminate constraints!

Step 1: Homogeneous Dirichlet BC's

$$\text{PDE: } -\nabla \cdot [bk \nabla h] = q_p = 1 \quad x \in [0, L]$$

$$\text{BC: } h(0) = h(L) = 0$$

Write BC as linear system:

$$\underline{\underline{B}} \underline{h} = \underline{0} \quad N_c \times \begin{array}{|c|} \hline \text{---} \\ \hline N_x \\ \hline \end{array} \begin{array}{|c|} \hline h \\ \hline \text{---} \\ \hline N_x \\ \hline \end{array} = \begin{array}{|c|} \hline \underline{0} \\ \hline \text{---} \\ \hline N_c \\ \hline \end{array}$$

$N_c$  = number of constraints

$$N_c \ll N_x$$

Full discrete problem

$$\begin{array}{l} \text{PDE: } \underline{\underline{L}} \underline{h} = \underline{f}_s \\ \text{BC: } \underline{\underline{B}} \underline{h} = \underline{0} \end{array} \quad \begin{array}{l} \underline{\underline{L}} \quad N_x \text{ by } N_x \quad \text{system matrix} \\ \underline{\underline{B}} \quad N_c \text{ by } N_x \quad \text{constraint matrix} \end{array}$$

Next time combine  $\underline{\underline{B}}$  and  $\underline{\underline{L}}$  into  
reduced linear system  $(N_x - N_c)$  by  $(N_x - N_c)$