

Numerical Jacobian

Given a system of non-linear algebraic equations, $\underline{r}(\underline{u}) = \underline{0}$, the most difficult step in applying the Newton-Raphson method is forming the Jacobian matrix $\underline{J} = \frac{d\underline{r}}{d\underline{u}}$

$$J_{ij} = \frac{\partial r_i}{\partial u_j} = \begin{pmatrix} \frac{\partial r_1}{\partial u_1} & \frac{\partial r_1}{\partial u_2} & \dots & \frac{\partial r_1}{\partial u_N} \\ \frac{\partial r_2}{\partial u_1} & \frac{\partial r_2}{\partial u_2} & & \frac{\partial r_2}{\partial u_N} \\ \frac{\partial r_3}{\partial u_1} & \frac{\partial r_3}{\partial u_2} & & \frac{\partial r_3}{\partial u_N} \\ \vdots & \vdots & & \vdots \\ \frac{\partial r_N}{\partial u_1} & \frac{\partial r_N}{\partial u_2} & & \frac{\partial r_N}{\partial u_N} \end{pmatrix}$$

$$\Rightarrow \underline{J} = \left[\frac{d\underline{r}}{du_1} \quad \frac{d\underline{r}}{du_2} \quad \frac{d\underline{r}}{du_3} \quad \dots \quad \frac{d\underline{r}}{du_4} \right]$$

The columns of \underline{J} can be created by perturbing one unknown at a time and compute the derivative with finite differences.

General code for numerical Jacobian

$[J] = \text{comp_jacobian}(\underline{r}, \underline{u}, \epsilon)$

residual
↓
unknown
↓
perturbation

↑
anonymous function

$n = \text{length}(\underline{u})$

$\underline{u_perturb} = \underline{u};$

for $i = 1 : n$

$\underline{u_perturb}(i) = \underline{u_perturb}(i) + \text{eps};$

$J(:, i) = (\underline{r}(\underline{u_perturb}) - \underline{r}(\underline{u})) / \epsilon;$

$\underline{u_perturb}(i) = \underline{u}(i);$

end

This approach works for any residual function, but it is generally expensive.

If $\underline{r}(\underline{u})$ is complicated it can be a separate function.

General outline

for $n = 1 : N$ % time-stepping loop

θ_{old} = θ % save old soln θ_{old} = θ ⁿ

while $\|res\| > tol \parallel \|nd\theta\| > tol \parallel k < k_{max}$

$$d\theta = -\underline{J}(\underline{\theta}) \setminus \underline{r}(\underline{\theta}, \underline{\theta}_{old})$$

$$\underline{\theta} = \underline{\theta} + d\theta$$

end

end