

Lecture 12: Transient heat Conduction

Logistic: HW4 due

HW5 → due Thu (radial coord.)

Last time: - Analytic Jacobian

- Radial coordinates

Today: Transient heat conduction

⇒ time evolution

Energy balance:

$$\text{PDE: } \underbrace{\rho c_p \frac{\partial T}{\partial t}}_{\text{new term}} - \nabla \cdot [\kappa \nabla T] = f_s$$

$$\text{BC: } T(H) = T_s \quad \mathbf{q} \cdot \mathbf{n}|_{z=0} = -|q_m|$$

$$\text{IC: } T(z, t=0) = T_0(z) \quad \text{initial condition (new)}$$

Discretize PDE:

$$\text{PDE: } \rho c_p \frac{\partial T}{\partial t} - \nabla \cdot \kappa \nabla T = f_s$$

$$? \quad - \underbrace{\underline{D} \underline{\kappa} \underline{G}}_{\underline{L}} \underline{u} = \underline{f}_s$$

\underline{L} = linear transport operator

New term (accumulation term):

1) time derivative: $\frac{\partial T}{\partial t} \approx \frac{\underline{u}^{n+1} - \underline{u}^n}{\Delta t}$

2) coefficients: $\rho(x) c_p(x) = \underline{\rho} \cdot \underline{c}_p$
 $N_x \cdot 1 \quad N_x \cdot 1$

$$\Rightarrow \underline{S} = \text{spdiags}(\underline{\rho} \cdot \underline{c}_p, 0, N_x, N_x)$$

substitute:

$$\underline{S} (\underline{u}^{n+1} - \underline{u}^n) + \Delta t \underline{L} \underline{u}^n = \Delta t \underline{f}_s + \Delta t \underline{f}_n$$

Theta Method

$$\underline{u}^b = \theta \underline{u}^n + (1-\theta) \underline{u}^{n+1}$$

θ = parameters

substitute

$$\underline{S} (\underline{u}^{n+1} - \underline{u}^n) + \Delta t \underline{L} [\theta \underline{u}^n + (1-\theta) \underline{u}^{n+1}] = \Delta t \underline{f}_s$$

\underline{u}^n is known \rightarrow r.h.s

\underline{u}^{n+1} is unknown \rightarrow l.h.s.

$$\underbrace{[\underline{S} + \Delta t (1-\theta) \underline{L}]}_{\underline{IM}} \underline{u}^{n+1} = \underbrace{[\underline{S} - \Delta t \theta \underline{L}]}_{\underline{EX}} \underline{u}^n + \Delta t \underline{f}_s$$

Linear system for n -th time step:

$$\underline{IM} \underline{u}^{n+1} = \underline{EX} \underline{u}^n + \Delta t \underline{f}_s$$

implicit matrix: $\underline{IM} = \underline{S} + \Delta t (1-\theta) \underline{L}$

explicit matrix: $\underline{EX} = \underline{S} - \Delta t \theta \underline{L}$

$$(\underline{L} = -\underline{D}^{-1} \underline{K} \underline{G})$$

Choice of $\theta \rightarrow$ determine method of time integration

Properties of θ -Method

$\theta=1$: Forward Euler Method

$\underline{IM} = \underline{S} \Rightarrow$ diagonal \Rightarrow cheap to invert

$$\underline{u}^{n+1} = \underline{S}^{-1} (\Delta t \underline{f}_s + \underline{EX} \underline{u}^n)$$

\Rightarrow explicit method to determine u^{n+1}

\hookrightarrow (no lin. sys. to solve)

\rightarrow first-order accurate

$$(\underline{u}^{n+1} - \underline{u}^n) + \Delta t \underline{L} \underline{u}^n = \Delta t \underline{f}_s$$

\Rightarrow one sided approx. of time deriv.

\rightarrow conditionally stable: $\Delta t \leq \frac{\Delta x^2}{2\alpha}$

$$\alpha = \frac{k}{\rho c_p} \text{ thermal diffusivity}$$

\Rightarrow many timesteps

$\theta=0$: Backward Euler Method

\underline{IM} not diagonal \Rightarrow solve lin. sys
at every timestep

\Rightarrow unconditionally stable

\rightarrow first-order (one sided approx.)

$\theta = \frac{1}{2}$: Crank-Nicholson Method

IM not diagonal \Rightarrow solve lru. sys.

\rightarrow second order in time because it
is centered in time.

\rightarrow unconditionally stable
(oscillation limit)

Amplification Matrix

$$\underline{f_s} = \underline{0}$$

at n -th time step: $\underline{IM} \underline{u}^{n+1} = \underline{EX} \underline{u}^n$

$$\underline{u}^{n+1} = \underbrace{\underline{IM}^{-1} \underline{EX}}_{\underline{A}} \underline{u}^n$$

A = amplification matrix

$$\underline{u}^{n+1} = \underline{A} \underline{u}^n$$

$$\underline{u}^n = \underline{A} \underline{u}^{n-1}$$

$$\underline{u}^{n+1} = \underline{A} \underline{u}^{n-2}$$

\Rightarrow

$$\underline{u}^n = \underline{A}^n \underline{u}^0$$

\underline{u}^0 initial condition

n-th power of a matrix

spectral decomposition: $\underline{A} = \underline{Q} \underline{\Lambda} \underline{Q}^{-1}$

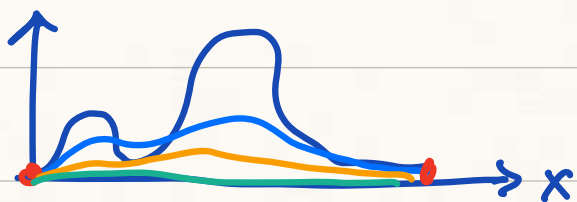
\underline{Q} = matrix of eigenvectors

$\underline{\Lambda}$ = diagonal matrix
of eigenvalues

$$\begin{aligned} \underline{A}^2 &= \underline{A} \underline{A} = \underline{Q} \underline{\Lambda} \underbrace{\underline{Q}^{-1} \underline{Q}}_{\underline{I}} \underline{\Lambda} \underline{Q} = \\ &= \underline{Q} \underline{\Lambda}^2 \underline{Q}^{-1} \end{aligned}$$

$$\Rightarrow \underline{A}^n = \underline{Q} \underline{\Lambda}^n \underline{Q}^{-1}$$

Heat conduction problem:



from physical intuition
we expect IC to decay
to zero (in absence of sources)

\Rightarrow for decay $|\lambda(\underline{A})| \leq 1$

Look at $\lambda(\Delta t)$ to find time step limit!

Instead of numerical analysis
we compute A and look at its eigenvalues! ▽